ABSTRACT: This paper introduces the fundamental continuum theory governing momentum transport in isotropic nanofluidic systems. The theory is an extension of the classical Navier–Stokes equation, and includes coupling between translational and rotational degrees of freedom as well as nonlocal response functions that incorporate spatial correlations. The continuum theory is compared with molecular dynamics simulation data for both relaxation processes and fluid flows, showing excellent agreement on the nanometer length scale. We also present practical tools to estimate when the extended theory should be used. It is shown that in the wall–fluid region the fluid molecules align with the wall, and in this region the isotropic model may fail and a full anisotropic description is necessary.

I. INTRODUCTION

Nanoscale devices can now be fabricated with channels where the smallest dimension is just a few nanometers, and the development of nanofluidic theory is more relevant than ever. Consider the following example. Persson et al. used a series of rectangular nanochannels with widths ranging from 14 to 300 nm to connect two microscale chambers. By means of capillary filling, fluid from one chamber fills up the channels and thus connects the two chambers. The filling rate was measured for different channel widths and for both Milli-Q water (filtered deionized water) and an electrolyte solution of sodium chloride. The rate did not follow the Washburn equation for channel widths smaller than 100 nm. The Washburn equation is based on the classical continuum picture using Poiseuille’s law of fluid motion, which includes the Newtonian (or macroscopic) shear viscosity. For widths larger than 100 nm the Washburn equation correctly predicts the filling rate. These findings are in accordance with the common understanding that the discrete nature of the fluid at small scales destroys the continuum picture. In fact, many researchers categorize continuum physics as physics on the macroscopic scale; see for example ref 7. Several questions immediately arise: When exactly does the classical continuum picture fail? How is this breakdown manifested? Does the length scale of the breakdown depend on the specific problem? Can one improve the continuum description such that it applies on small scales?

Demanding sufficient smoothness of the macroscopic quantities with respect to time and position and using a simple statistical argument, Lautrup estimates that the smallest volume accessible to the continuum description must contain at least $10^7$ molecules. This corresponds to a length scale of 8–80 nm, depending on the density. For steady flows the temporal fluctuations can be averaged out and the accessible volume is much smaller. This is illustrated in Figure 1, where we have performed

![Figure 1. Comparison between atomistic simulations (blue filled circles) and the continuum prediction (red lines) for a methane fluid undergoing a Poiseuille flow. The flow is generated by an external force field with magnitude $F = 50 \text{ kN}$, pointing along the $x$ direction. The Navier–Stokes equation predicts a velocity profile of $u_x(z) = \rho F / (2\eta_0)(h^2 - z^2) + u_w$, where $\rho = 270 \text{ kg m}^{-3}$ is the mass density, $\eta_0 = 9.3 \pm 0.6 \mu \text{ Pa s}$ is the Newtonian shear viscosity, and $u_w = 62 \text{ m s}^{-1}$ is the fluid slip velocity at the wall surface. The two lines represent the interval associated with the standard error in the viscosity. The width of the slit pore is approximately 10 molecular diameters or 3.3 nm.](image-url)
an atomistic simulation (data given by blue filled circles) of a methane fluid confined between two graphene sheets undergoing Poiseuille flow. The slit pore has a width of approximately 3.3 nm, and the flow is driven by an external force field. The classical continuum prediction is plotted as two red lines illustrating the maximum and minimum profiles allowed within statistical uncertainty on the Newtonian shear viscosity. Only the fluid slip velocity at the wall surface is used as a fitting parameter. For this system the continuum theory gives a satisfactory description of the fluid steady state velocity profile on a length scale of a few nanometers. Apparently, even on these small length scales the molecular structure and degrees of freedom can be coarsened into simple transport coefficients such as the viscosity. For water undergoing a steady flow it has been shown by atomistic simulations that the continuum description holds for channel widths of just 6–10 nm. These results contrast earlier assumptions about the validity of the continuum picture and the statement that continuum physics is physics on the macroscopic scale. Interestingly, it was later argued by Thamdrup et al. that the disagreement between the experiment by Persson et al. and the Washburn prediction is due to pinned microripples resulting in an increase in hydraulic resistance.

At some point the classical continuum description will of course break down. To mention two examples, Travis et al. showed that for atomic fluidic systems the velocity profile features modulations for confinements on the order of 5 atomic diameters. Decheverry and Bocquet analyzed the effect of thermal fluctuations on the mass transport of fluid through a nanotube. When the classical continuum theory fails, the dynamics is frequently quantified by different transport coefficients compared to those of the bulk system, and effective transport coefficients are introduced into the continuum constitutive relations. The main point of this paper is that the observation of a breakdown need not be a failure of the continuum picture itself but rather a result of inadequate modeling wherein important dynamical processes are not accounted for by classical theories. A very well understood example is the effect of the Debye screening layer in electrolyte microflows. Two other physical mechanisms that become important on the nanoscale are often ignored in the literature, however, and this paper will treat these in detail: (i) In classical hydrodynamics the fluid’s local rotation is determined uniquely by the fluid streaming velocity. One can quantify the rotation from the local angular velocity field which is one-half the vorticity, that is, one-half the curl of the streaming velocity itself. However, if the couple force, that is, the force component producing pure rotation, is large, then the rotation must be treated as an independent variable. The extended description is known as Cosserat (or micropolar) continuum mechanics first formulated by the Cosserat brothers in the late 19th century. Cosserat continuum theory is used in various areas such as liquid crystal studies and blood flows, and was studied intensively in the 1950s to 1970s; see refs 21–27. For some reason it is not, however, adopted by the nanofluidic community. We show that Cosserat theory must also be used for fluid flows in extremely small confinements where the molecular structure becomes important. (ii) Classical hydrodynamics is based on local constitutive relations relating fluxes to thermodynamic forces. For shear flow the stress at some point depends on the strain rate at that particular point. If the stress depends linearly on the strain rate, then this leads to the Newtonian law of viscosity. A more general linear constitutive relation is to let the stress be a function of the entire strain rate history and spatial distribution, i.e., given by a spatial and temporal convolution integral of a viscosity kernel and the strain rate. This is the approach of generalized linear response theory. The viscosity kernel accounts for the characteristic length scale of the spatial correlations; we show later that this must be taken into account in order to arrive at the correct fluid response on molecular length scales.

Our presentation is based on comparisons of continuum predictions with atomistic molecular dynamics (MD) simulation data. These two descriptions are fundamentally different in two ways. First, in MD the system is characterized by discrete particles where the path of each individual particle constituting the fluid is traced out through classical mechanics; the particle interactions must be known. The discretization of matter is, of course, in strong contrast to the fundamental assumptions of continuum mechanics. Second, the continuum description applies constitutive relations to form mathematical closed problems. No such models are enforced in the standard MD simulations. Any discrepancy between MD and the continuum description may therefore be a result of a breakdown of the constitutive relation rather than a breakdown of the continuum theory as such. Our basic conjecture is that MD acts as an idealized numerical experiment, and if a given continuum theory agrees with the MD data, then the theory correctly accounts for the phenomena we study.

Let us specify more accurately what is meant by continuum theory. Basically, one refers to deformable fluid volumes characterized by quantities which are continuous at any point over the entire volume and at any time. This means that these quantities are described mathematically by field variables. The basic continuum hypothesis is that one can associate a given fluid subvolume (or “fluid particle”) with the same characteristic quantities of the entire deformable fluid volume, no matter how small the subvolume. Lautrup suggests a lower limit on the order of 10⁴ molecules as stated previously, but averaging allows an arbitrarily small fluid particle volume as seen in Figure 1. One field variable is the streaming velocity, which is the mass-weighted average velocity of the individual molecules in the fluid particle around a given point. The fluid’s dynamics is governed by balance (or conservation) equations. In general the balance equation for some quantity per unit mass, φ = ϕ(r, t), reads in the Eulerian differential form as

\[ \frac{\partial (\rho \phi)}{\partial t} + \nabla \cdot (\rho u \phi) = \sigma_\phi - \nabla \cdot J_\phi \]

where \( \rho \) is the mass density, \( \sigma_\phi \) is a production term, \( u \) is the streaming velocity, and \( J_\phi \) is the flux of \( \phi \). Here \( \phi \) can be a scalar or vector quantity. For \( \phi = u \), the right-hand side of eq 1 is the sum of the body force and the surface force densities, that is, forces per unit volume and eq 1 is the momentum balance equation. The body force density can be a gravitational-like force driving the flow as in Figure 1, and the surface force density is the pressure tensor \( J_\phi \) is the pressure tensor \( P \). A special case is the mass balance equation for which \( \phi = 1 \). Since rotation is treated as an independent variable, a balance equation in the form of eq 1 must be formulated for rotation; this is done in the Supporting Information (SI). Importantly, in the extended Cosserat description the pressure tensor \( P \) need not be symmetric and \( \sigma_\phi \) as in the classical continuum theory.

A comparison between the continuum description and MD simulation data is carried out for molecular fluidic systems at equilibrium as well as for steady flows in a slit pore. Here we investigate four molecular fluids: a methane fluid, a generic diatomic (dumbbell) fluid, liquid butane, and liquid water. For
methane 75% of the mass is centered in the carbon nucleus, and methane is treated here to be a simple spherical point-mass molecule, as was done in Figure 1. Water will, on the other hand, be treated differently using the flexible SPC/Fw water model\textsuperscript{34} that accounts for the molecular structure and hydrogen bonds and thus for the structure of liquid water. The butane model is a coarse-grained model where the methyl and methylene groups are each represented by a united atomic unit, i.e., a spherical point mass. Details about the butane model can be found in ref \textsuperscript{35}; however, flexible bonds are implemented with parameters from the generalized Amber force field\textsuperscript{36}. The simulations are done using the seplib library.\textsuperscript{37}

Nano-fluidic flows are often associated with fluid slippage at the wall boundary.\textsuperscript{38} Just like the effect of the fluid–fluid interactions is lumped into a single parameter, e.g., viscosity, the effect from the fluid–solid interaction can be modeled into a friction coefficient determining the boundary slip. The slippage has a large effect on the flow rate in extreme confinement and is usually quantified by the slip length \( L_s \). For a Hagen–Poiseuille flow in a tube with radius \( R \), the relative flow enhancement \( \Delta E^{rl} \) due to the slip is given as\textsuperscript{39}

\[
\Delta E^{rl} = 1 + \frac{4L_s}{R}
\]  

(2)

\( L_s \) is typically on the order of a few nanometers. Thus, for a given nonzero slip length the flow enhancement increases hyperbolically as the tube radius decreases. The slip is always present but has an insignificant effect on the flow rate for tube radii greater than micrometers. \( L_s \) is normally independent of system size; that is, it is not an intrinsic nano-fluidic phenomenon and is therefore not addressed in this paper. Slippage is modeled here in an ad hoc fashion as was done in Figure 1.

In the SI we derive the Cosserat extended continuum theory from the microscopic point of view using a microscopic hydrodynamic operator. The derivation, which is based on the fundamental definition of the macroscopic field variables in terms of the corresponding molecular quantities, follows the ideas of Irving and Kirkwood\textsuperscript{30} and Evans and Morriss;\textsuperscript{31} see also ref \textsuperscript{41}. The derivation leads to a molecular interpretation of the fluxes entering eq 1. The final dynamical system of equations is sometimes referred to as the extended Navier–Stokes (ENS) equations; these are given by

\[
\rho \frac{Du}{Dt} = \sigma_u - V\Pi_s + \left( \eta_v + \frac{\eta_0}{3} - \eta_r \right) \nabla(\nabla \cdot u) + (\eta_0 + \eta_r) \nabla^2 u + 2n\eta \nabla \times \Omega
\]

\[= \sigma_u + 2n(\nabla \cdot u - 2\Omega) + \left( \xi_v + \zeta_0 - \xi_r \right) \nabla(\nabla \cdot \Omega) + (\zeta_0 + \zeta_r) \nabla^2 \Omega
\]  

(3a)

where \( D/\text{Dt} \) is the material operator, \( \Omega \) is the spin angular velocity field, \( V\Pi \) is the pressure gradient, and \( I \) is the moment of inertia per unit mass. Transport coefficients \( \eta_v, \eta_0, \) and \( \eta_r \) are the bulk, shear, and rotational viscosities, respectively, and \( \zeta_0, \zeta_r \) and \( \zeta_0 \) are the corresponding spin viscosities. Finally, inertia per unit mass, \( \sigma_u \) and \( \sigma_s \), represent production terms of linear and spin angular momentum, respectively. We refer the reader to the SI for a derivation and discussion of eq 3.

The theory is strictly correct only for isotropic systems, and we study such nanofluidic cases in sections II and III, comparing theoretical predictions with MD simulation data. Flows in extreme confinement, nanoflows, are characterized by strong density inhomogeneities and anisotropy. We study such flows in section IV, again comparing theory with MD data. Finally, section V gives a brief summary.

II. COUPLING: MULTISCALE RELAXATION PHENOMENA IN MOLECULAR FLUIDS

The purpose of this section is to demonstrate the validity of the ENS equations, eqs 3, by comparing the predictions of different thermally induced relaxation phenomena with MD simulation data;\textsuperscript{32} see also refs \textsuperscript{42} and \textsuperscript{43}. We start with this problem instead of the situation with confining walls as the latter introduces density inhomogeneities and molecular alignment at the wall–fluid interface. We return to this more complex situation in section IV.

Rather than investigating the quantities directly, one typically studies the associated correlations.\textsuperscript{44} Here we will use the approach based on Onsager’s regression hypothesis,\textsuperscript{45} which states that thermal perturbations on average decay according to the deterministic hydrodynamic equations of motion. Specifically, we will compare mechanical spectra obtained from MD simulations with predictions from eq 3.

A. Stochastic ENS Equations. In equilibrium, a fluctuating quantity \( A \) can be written as \( A = A_0 + \delta A \), where \( A_0 \) is the average part and \( \delta A \) is the fluctuating part. In equilibrium, the average streamwise velocity and spin angular velocity are both zero, so \( u = \delta u \) and \( \Omega = \delta \Omega \). The fluctuations are modeled using the stochastic forcing approach.\textsuperscript{46} Here an uncorrelated zero mean stochastic force is added to the constitutive relations; see the SI. For example, for the antisymmetric pressure the constitutive relation with stochastic forcing reads

\[
\delta P = -\eta_r (\nabla \times \delta u - 2\delta \Omega) + \delta P
\]

where \( \delta P \) is the stochastic fluctuating part of the flux.

To a first-order approximation in the fluctuation we have on the left-hand side of eq 3

\[
(\rho_v + \delta \rho) \frac{D\delta u}{Dt} \approx \rho_v \frac{\partial \delta u}{\partial t}
\]

(4)

and

\[
(\rho_v + \delta \rho)(L_v + \delta l) \frac{D\delta \Omega}{Dt} \approx \rho_v L_v \frac{\partial \delta \Omega}{\partial t}
\]

(5)

In Fourier space the stochastic ENS equations read first order in the fluctuations for wave vector \( k \)

\[
\rho_v \frac{\partial \delta u}{\partial t} = -ik\delta q - \left( \eta_v + \frac{\eta_0}{3} - \eta_r \right) k(k \delta u) - (\eta_0 + \eta_r) k^2 \delta u + 2n\eta k \times \delta \Omega + ik \delta P
\]

(6a)

\[
\rho_v \frac{\partial \delta \Omega}{\partial t} = 2\eta (ik \times \delta u - 2\delta \Omega) - \left( \xi_v + \frac{\xi_0}{3} - \xi_r \right) k(k \delta \Omega) - (\zeta_0 + \zeta_r) k^2 \delta \Omega + ik \delta \Omega + 2\delta P
\]

(6b)

due to the properties of the divergence operator. The Fourier transform is defined by eq 2 SI. It is convenient here to introduce the following coefficients

\[
\eta = \eta_v + \eta_r, \quad \zeta = \zeta_0 + \zeta_r, \quad \text{and} \quad \xi = \zeta_v + \frac{4\zeta_0}{3}
\]

(7)

where subscript t indicates transverse and subscript l indicates longitudinal. It has been shown\textsuperscript{27,42} that \( \xi \approx \zeta_0 \) and we write...
both coefficients as ζ. We may then define the susceptibility as
\[ \chi(k^2) = 4\eta_k + k^2 \]
where \( k^2 = k^2 \). We will also drop the subscript av from here on.

We take \( k = (0, k_y, 0) \) and write out the \( x \) component of the velocity and the \( z \) component of the angular velocity
\[
\rho \frac{\partial \bar{u}_x}{\partial t} = -\eta_k k_y \bar{\Omega}_z + ik \bar{\Omega}_{xy}.
\]
\[
\rho \frac{\partial \bar{\Omega}_z}{\partial t} = -\chi(k^2) \bar{\Omega}_x - 2\eta_k k_y \bar{\Omega}_z + i\bar{\Omega}_{xy} + 2 \bar{q}_z
\]
(9a)
(9b)

These two components are both transverse components to the wave vector and are coupled. We also investigate the longitudinal angular velocity component \( \bar{\Omega}_y \), which is given through
\[
\rho \frac{\partial \bar{\Omega}_y}{\partial t} = -\chi(k^2) \bar{\Omega}_x + ik \bar{\Omega}_{xy} + 2 \bar{q}_y.
\]
(9c)

Note that this longitudinal component is unaffected by the coupling between the linear and spin angular momenta.
We define the following three correlation functions
\[
C_{1\text{uu}}(\mathbf{k}, t) = \frac{\langle \bar{u}_x(\mathbf{k}, t) \bar{u}_x(\mathbf{-k}, 0) \rangle}{V}
\]
\[
C_{1\text{uu}}(\mathbf{k}, t) = \frac{\langle \bar{\Omega}_x(\mathbf{k}, t) \bar{\Omega}_x(\mathbf{-k}, 0) \rangle}{V}
\]
\[
C_{1\text{uu}}(\mathbf{k}, t) = \frac{\langle \bar{\Omega}_y(\mathbf{-k}, t) \bar{\Omega}_y(\mathbf{-k}, 0) \rangle}{V}
\]
which we denote the transverse velocity autocorrelation function (TVACF), the transverse cross-correlation function (TCCF), and the longitudinal angular velocity autocorrelation function (LAVACF), respectively. By assumption, the fluctuating fluxes are uncorrelated with the velocity and angular velocity, e.g., \( \langle \bar{q}_x \bar{u}_y \rangle = 0 \). Thus, by multiplying eqs 9a and 9b by \( \bar{u}_x(\mathbf{-k}, 0) \) and ensemble averaging, we arrive at the differential equation system for the TVACF and the TCCF
\[
\rho \frac{\partial C_{1\text{uu}}}{\partial t} = -\eta_k k^2 C_{1\text{uu}} + 2\eta_k k_y C_{1\text{uu}}
\]
\[
\rho \frac{\partial C_{1\text{uu}}}{\partial t} = -\chi(k^2) C_{1\text{uu}} - 2\eta_k k_y C_{1\text{uu}}
\]
(10a)
(10b)

Similarly, by multiplying eq 10 by \( \bar{\Omega}_y(\mathbf{-k}, 0) \) one has for the LAVACF
\[
\rho \frac{\partial C_{1\text{uu}}}{\partial t} = -\chi(k^2) C_{1\text{uu}}
\]
(11a)
(11b)
(11c)

\[ C_{1\text{uu}}(\mathbf{k}, t) = \frac{9k_BT}{4\rho l^2} e^{-\omega_0 t} \]
(14a)

where the characteristic frequencies are
\[ a_0 = \frac{\chi(k^2)}{\rho l^2}, \quad a_1 = \frac{\chi(k^2) + i\eta_k k^2}{\rho l}, \quad \text{and} \quad a_2 = \frac{\eta_k k^2}{\rho} \]
(15)

The prefactors in eqs 14c and 14a are calculated from the first-order approximation in the fluctuations
\[ \bar{u}(\mathbf{k}, t) \approx \frac{m}{\rho} \sum_i c_i e^{-i\mathbf{k} \cdot \mathbf{r}_i} \]
(16)

where \( m \) is the molecular mass, \( c \) the thermal center-of-mass velocity, and \( \mathbf{r}_i \) is the center-of-mass position of molecule \( i \). This comes from the definition of the linear momentum density (SI eq 14). Likewise, to a first-order approximation in density fluctuations and moment of inertia \( \rho \mathbf{S} \approx \rho \mathbf{I} \Omega \), and from SI eq 29
\[ \bar{\Omega}(\mathbf{k}, t) \approx \frac{3m}{2\rho} \sum_i \Omega_i e^{-i\mathbf{k} \cdot \mathbf{r}_i} \]
(17)

as \( I = \frac{I_p}{3} \) where \( I_p \) is the principle moment of inertia.\(^{47}\) By applying the equipartition theorem, one arrives at the prefactors.

Equations 16 and 17 also provide a first-order method to calculate the correlation functions in the MD simulations; this method is used here.

It is informative to work in the frequency domain, i.e., to predict the peak frequencies in the corresponding spectra. Applying the Fourier–Laplace transform defined by
\[ \mathcal{L}[f](\mathbf{k}, \omega) = \int_0^\infty f(\mathbf{k}, t) e^{-i\omega t} dt \]
we get
\[ C_{1\text{uu}}(\mathbf{k}, \omega) = -\frac{k_BT}{4\rho \left( \omega_0 + i\omega \right)} \left( 4 + \frac{\eta_k k^2}{\omega_0 + i\omega} \right) \]
(19a)
\[ C_{1\text{uu}}(\mathbf{k}, \omega) = -\frac{i\eta_k k}{\chi(k^2) + i(\eta_\gamma - \eta_\rho) k^2} \left( \frac{1}{\omega_0 + i\omega} - \frac{1}{\omega_2 + i\omega} \right) \]
(19b)
\[ C_{1\text{uu}}(\mathbf{k}, \omega) = \frac{9k_BT}{4\rho l^2} \frac{1}{\omega_0 + i\omega} \]
(19c)

From eq 19b we can make a very important conclusion, namely,
\[ C_{1\text{uu}}(\mathbf{k}, \omega) \to 0 \text{ for } \mathbf{k} \to 0 \]
(20)
This means that the coupling can be ignored on long length scales. This is also expected as the classical Navier–Stokes theory holds for macroscopic systems where no coupling effect is observed. The relaxation of spin is still governed by the rotational viscosity, but this relaxation does not affect the relaxation of the linear momentum controlled by the usual viscous dissipation processes. If we define \( \alpha_0 \) as
\[ \alpha_0 = \lim_{\mathbf{k} \to 0} \frac{a_0}{\rho l} \]
(21)
then LAVACF and TVACF are, in the limit of zero wave vector,
\[ C_{\|}^\perp(\omega) = \frac{9k_B T}{4\rho} \frac{1}{\omega_1 + i\omega} \quad \text{and} \]
\[ C_{\mu}^\perp(k, \omega) = \frac{k_B T}{\rho} \frac{1}{\omega_2 + i\omega} (k \rightarrow 0) \]  

(22)

Furthermore, for the fluids studied here the effect of the coupling on the TVACF is not large, that is,
\[ \left| \frac{k^2}{\omega_1 + i\omega} \right| < \left| \frac{4 + k^2}{\omega_2 + i\omega} \right| \]  

(23)

even for wave vectors in the submolecular diameter range, and the limit in eq 22 need not be taken as a strict limit. It is worth noticing that the rotational viscosity \( \eta_i \) is a linear function of the moment of inertia \( I \) for sufficiently large \( I \), so \( \omega_i \) is independent of \( I \) here.

B. Comparison with Molecular Dynamics. We first compare the predictions from the continuum ENS theory with MD simulation data for the simple diatomic molecule (the dumbbell model) in the supercritical fluid regime. Transport coefficients \( \eta_{\|}, \zeta, \) and \( \eta_r \) are listed in Table 1 in the SI.

Figure 2 shows MD data (symbols connected with lines) for imaginary parts of the spectra of the TVACF and LAVACF; normalization is carried out for clarity. The prediction from the continuum theory is plotted as solid blue lines. It is observed that for small wave vectors \( k = 2\pi/\lambda \) the continuum prediction is in excellent agreement with the MD data, but it fails for larger wave vectors \( k = 20\pi/\lambda \). We emphasize that no fitting is performed, and all relevant parameters are taken from SI Table 1 found from independent simulations and methods. Using typical values for MD units \( \sigma, \epsilon, \) and \( m \), the results show that the continuum theory predicts the mechanical spectrum for wavelengths on the order of 2–3 nm and above and time scales on the order of 1–10 ps and above.

For the TVACF, Figure 2(b), the result can be understood from the fluid stress relaxation at zero wave vector as suggested by Bocquet and Charlaix. From the last equation in eq 15, we can define a wave-vector-dependent relaxation time \( \tau_s = 2\pi\rho/(\eta_k k^2) \). This relaxation time must be larger than the characteristic relaxation time \( \tau_c \) at zero wave vector for the predictions to hold for \( \tau_s / \tau_c < \eta_k ), i.e., for the viscosity to be wave-vector-independent. This means that
\[ \frac{\eta_k \tau_s}{2\pi\rho} < 1 \quad \text{or} \quad k < \frac{2\pi\rho}{\eta_k \tau_c} \]

(24)

We refer to this as the Bocquet–Charlaix criterion. Estimates for the relaxation time \( \tau_c \) are given through the shear stress (or equivalently stress) autocorrelator
\[ G(t) = \frac{V}{k_B T} \langle \xi y(t) \xi y(0) \rangle \]

(25)

where \( \xi y \) is the \((x, y)\) component of the traceless symmetric part of the pressure tensor. For the dumbbell model \( G(t) \) is fully decayed at \( \tau_c \approx 3\sigma/m(\rho/e)^{1/2} \), which gives \( k < 1.2 \pi \). This is in perfect agreement with the results depicted in Figure 2(b). Alternatively, the relaxation time can be given through the Maxwell relaxation time \( \tau_M = \eta_k / G_{\|} \) or the viscous relaxation time \( \tau_v = \Psi_{\|0}/\eta_k \) where \( G_{\|} \) is the infinite shear modulus and \( \Psi_{\|0} \) is the first normal stress coefficient. For the diatomic model studied here, \( \tau_M \approx \tau_c \approx 0.05\sigma/m(\rho/e)^{1/2} \) giving \( k < 9.4 \pi \), which is not what is observed. Therefore, the characteristic decay time that should be used for the Bocquet–Charlaix criterion is the time for the autocorrelation function \( G(t) \) to decay fully.

In the small wave vector regime the relaxation of spin angular momentum is dominated by the coupling mechanism between linear and angular momenta as the peak is located at \( \omega_0 \approx \omega_s = 4\eta_k/(\rho l) \). The relaxation of linear momentum, Figure 2(b), is on the other hand due to usual viscous mechanisms seen by the peak frequency \( \omega_0 \approx \eta_k k^2/\rho \). For large \( k \) the continuum theory overestimates, by an order of magnitude, the peak frequency for the LAVACF and TVACF due to overestimation of the effect of the spin diffusion.
The shear viscosity kernel \( \tilde{\eta}(k, \omega) \) can be found from the TVACF as it is now shown. Here we focus on molecules with small moments of inertia and small wave vector regimes, i.e., small \( k^2 \). In this limit eq 19a can be rearranged to give

\[
\tilde{\eta}(k, \omega) = \frac{k_B T}{k^2 C_{uu}(k, \omega)} (\text{small } k^2)
\]

In particular, we have at zero frequency

\[
\tilde{\eta}(k, 0) = \frac{k_B T}{k^2 C_{uu}(k, 0)} (\text{small } k^2)
\]

This approximation holds even for large values of \( k^2 \) as discussed above (eq 23). For molecules that can be regarded as point masses, say methane, the moment of inertia is zero and eq 28 is exact. In Figure 4(a) the viscosity kernel at zero frequency is plotted for the methane, dumbbell, butane, and water systems using eq 29. One immediately notices that for \( k \approx 10^{-1} \) the wave-vector-dependent viscosity approaches the zero wave vector limit. This is in good agreement with the Bocquet–Charlaix criterion (eq 24). Interestingly, this is independent of the specific fluid studied here, and the local constitutive relations can be applied on length scales down to approximately \( 2\pi/k \approx 2–2.5 \) nm.

Is this a general result that applies to all fluidic systems? The answer is no! In Figure 4(b) the zero-frequency viscosity kernel is plotted for the asymmetric dumbbell model for different temperatures. The asymmetry arises due to the mass and Lennard-Jones parameter differences between the two constituent atoms. The asymmetric dumbbell model allows one to probe the dynamics in the highly viscous regime without crystallization occurring. The result shows that for relatively high temperatures the kernel has the same wave vector dependency, but on approaching the viscous regime (lower temperature) the kernel reaches the Newtonian viscosity only at longer length scales. This indicates that the dynamical processes behind the viscous response take place on longer length scales in accordance with the cooperative motion in supercooled liquids. The nonlocal viscous response has also been studied for highly viscous two-component Lennard-Jones systems and polymer melts (refs 31 and 32).

The failure of the local constitutive relation, that is, of Newton’s law of viscosity, is very clearly illustrated by Todd et al. for a point-mass Weeks–Chandler–Andersen (WCA) system. In real space the nonlocal description amounts to a convolution of the viscosity kernel and the strain rate distribution (eq 26). In the homogeneous situation where the fluid undergoes a steady shear in the \( x \) direction with varying amplitude in the \( z \) direction we have one nonzero shear component in the pressure tensor,
namely, the $P_{xz}$ component. In this steady situation eq 26 reduces to

$$P_{xz}(z) = -\int_{-\infty}^{\infty} \eta(z-z') \dot{\gamma}(z') \, dz'$$  \hspace{1cm} (30)

where $\dot{\gamma}(z) = \partial u_z(z)/\partial z$. If the shear is induced by an external force field $F_x(z) = F_0 \cos(kz)$, then the fluid flow is $u_z(z) = \tilde{u}_z \cos(kz)$, where $\tilde{u}_z$ is the excited Fourier mode amplitude of the velocity field. We assume that this is the only mode excited, i.e., the force amplitude must be sufficiently low. Also, this ensures a linear response as well as constant temperature and density. The strain rate is then

$$\dot{\gamma}(z) = -k\tilde{u}_z \sin(kz)$$  \hspace{1cm} (31)

For simplicity we shall assume that the kernel is given by a Gaussian function

$$\eta(z) = \eta_0 \sqrt{\frac{\alpha}{\pi}} e^{-\alpha z^2}$$  \hspace{1cm} (32)

such that $1/\alpha^{1/2}$ gives a characteristic decay length. The kernel must fulfill (i) $\int_{-\infty}^{\infty} \eta(z) \, dz = \eta_0$ and (ii) $\eta(z)$ is an even function. Substituting eqs 31 and 32 into eq 30 we have upon integration

$$P_{xz}(z) = \eta_0 k \tilde{u}_z e^{-k^2/4\alpha} \sin(kz)$$  \hspace{1cm} (33)

If $\eta(z) = \eta_0 \delta(z)$ then the model is local, corresponding to Newton’s law of viscosity, that is, for the local model

$$P_{xz}^L(z) = -\eta_0 \dot{\gamma} = \eta_0 k \tilde{u}_z \sin(kz)$$  \hspace{1cm} (34)

The system can be simulated using the sinusoidal transverse force (STF) method,\(^5_7^7\) and it is possible to evaluate $\tilde{u}_z$ for different external force fields and wave vectors. The two different predictions can be compared to the actual shear pressure $P_{xz}^A$, which is found directly from the momentum balance equation that for the steady flow reads

$$\frac{\partial}{\partial z} P_{xz}^A(z) = \rho F_x$$  \hspace{1cm} (35)

Upon integrating we obtain

$$P_{xz}^A(z) = \frac{\rho F_0}{k} \sin(kz)$$  \hspace{1cm} (36)

The comparison is made in Figure 5. Clearly, the local prediction fails for the larger wave vector (Figure 5(b)), whereas the nonlocal prediction agrees with the actual shear pressure. From the nonlocal model we conclude that spatial correlations result in a reduced shear pressure.

From eqs 33 and 34 we can quantitatively evaluate the effect of spatial correlations on the stress. Specifically, we have the relative difference given by

$$\Delta P_{xz}^{rel} = 1 - \frac{P_{xz}^L}{P_{xz}^A} = 1 - e^{-k^2/4\alpha}$$  \hspace{1cm} (37)

For the WCA system studied here, $\tau_s \approx 0.6\sigma (m/\epsilon)^{1/2}$, and the Bocquet–Chairlaix criterion gives $k < 2.8\alpha^{-1}$, which corresponds to an error in the local stress up to around 32% according to eq 37.

The Gaussian function does not fit perfectly to the kernel data. Nevertheless, this simple functional form captures the nonlocal response well due to the smoothing of the convolution.
Other more complicated functions have been suggested; see refs 31, 51, and 58.

Todd and Hansen59 showed that the nonlocal response is relevant only for flows where the strain rate is nonlinear with respect to position. Couette and Poiseuille flows are then not affected by nonlocality. To illustrate this consider any functional form for the kernel which fulfills the criteria given above: its integral gives the zero wave vector viscosity, and it is an even function with respect to \( z \). First, making the change in variables \( u = z - z' \), eq 30 reads

\[
P_{\alpha}(z) = -\int_{-\infty}^{0} \eta(u) \gamma(z - u) \, du
\]

Assuming a strain rate of the form \( \gamma(z) = az \), we have

\[
P_{\alpha}(z) = -az \int_{-\infty}^{0} \eta(u) \, du + a \int_{-\infty}^{0} \eta(u) u \, du = -an_{0} \zeta
\]

because the integrand in the second integral is an odd function. This result is the same as the local prediction. In general, if a Taylor expansion of the strain rate \( \gamma = a_{0} + a_{1}z + \ldots + a_{n}z^{n} + \ldots \) exists, then using the properties of odd and even functions one can verify that the nonzero nonlocal effects of the strain rate can be determined by the even moments of the kernel.

In the case of Couette and Poiseuille flows the Taylor expansion terminates at zeroth and first order, respectively, and there are no nonlocal effects.

Finally, the spin and rotational viscosity kernels can be found by simply rearranging eq 19c to give the generalized susceptibility

\[
\chi(k, \omega) = \frac{\frac{g}{4} k_{B} T - i \omega \Pi_{l} H_{H}(k, \omega)}{c_{3} H_{H}(k, \omega)}
\]

Our group recently42,43 conjectured that the rotational viscosity \( \eta_{r} \) governs the fast wave vector independent relaxation processes as indicated in Figures 2(a) and 3(a). This transport coefficient is therefore only frequency-dependent. We then have

\[
\tilde{\chi}(k, \omega) = 4\tilde{\eta}_{r}(\omega) + \tilde{\zeta}(k, \omega)k^{2}
\]

and therefore

\[
\tilde{\eta}_{r}(\omega) = \frac{1}{4k} \lim_{k \to 0} \tilde{\chi}(k, \omega) \quad \text{and} \quad \tilde{\zeta}(k, \omega) = \frac{\tilde{\chi}(k, \omega) - 4\tilde{\eta}_{r}(\omega)}{k^{2}}
\]

We called this the generalized extended Navier–Stokes (GENS) theory. From MD simulations one can calculate the LAVACF (as shown above) and from there find the kernels. For dense fluids \( \tilde{\zeta} \) is characterized by a sharp peak around zero wave vector45 since the diffusive contribution to the relaxation of the LAVACF is very small for \( k > 2\pi/L \); see Figures 2(a) and 3(a). The spin viscosity kernel has the same properties as the shear viscosity kernel, and for this reason we do not expect any nonlocal effects for flows where the gradient of the angular velocity is constant or linear.

### IV. NANOFLOWS

Until now we have only considered isotropic and unconfined systems. We will use the information gathered in the next study where the fluids flow in extreme confinements.

#### A. Poiseuille Flow

We first study a Poiseuille flow; the geometry is shown in Figure 1. In experiments this flow can be achieved by the application of a constant pressure gradient. Generating a pressure difference in simulations with, for example, a piston and using molecular reservoirs can cause density variations in the direction of the flow and other inlet/outlet effects. We therefore use a constant force field acting on each point mass in the fluid to drive the flow. The wall particles are arranged on a simple cubic lattice and are allowed to vibrate around their initial lattice site using a simple restoring spring force. The viscous heating generated in the fluid is removed by thermostating the wall particles. This method resembles a real physical experiment and is therefore often referred to as direct nonequilibrium molecular dynamics. The interested reader is referred to ref 11 for further details. To get a satisfactory signal-to-noise ratio in the MD simulations, unrealistically large external forces are typically applied to drive the system, and the resulting flow rates are very large, typically on the order of 10–100 m s\(^{-1}\). Despite these large flow rates the Reynolds number is usually less than unity due to the extremely small characteristic length scales involved. It is very important to ensure that the simulations are carried out in the linear regime, which is discussed below.

1. **Continuum Predictions.** In the linear regime and for the geometry shown in Figure 1 the ENS equations form a two-point boundary value problem in the steady state

\[
\rho_{f} \frac{d^{2}u_{f}}{dz^{2}} - 2\eta_{r} \frac{d\Omega}{dz} = 0 \quad \text{(44a)}
\]

\[
2\eta_{r} \left( \frac{d\Omega}{dz} - 2\Omega \right) + \frac{d^{2}\Omega}{dz^{2}} = 0 \quad \text{(44b)}
\]

for \(-h \leq z \leq h\). Recall that \( \eta_{r} = \eta_{0} + \eta_{r} \) and \( \zeta = \zeta_{0} + \zeta_{r} \). Introducing \( z' = z/h \), \(-1 \leq z' \leq 1\), and applying no-slip boundary conditions, \( u_{r}(-1) = u_{r}(1) = 0 \) and \( \Omega_{r}(-1) = \Omega_{r}(1) = 0 \), Eringen\(^{23}\) solved this, yielding

\[
u_{r}(z') = u_{r} \left( 1 - z'^{2} + \frac{2\eta_{r}}{\eta_{0}} \coth(Kh) \left( \frac{\cosh(Khz')}{\cosh(Kh)} - 1 \right) \right)
\]

(45a)

\[
\Omega_{r}(z') = \frac{u_{r}}{h} \left( \frac{\sinh(Khz')}{\sinh(Kh)} - z' \right)
\]

(45b)

with the following definitions of \( u_{r} \) and \( K \)

\[
u_{r} = \frac{k^{3} \rho_{f}}{2\eta_{0}} \quad \text{and} \quad K = \left( \frac{4\eta_{r}/\zeta_{r}}{\zeta_{r}} \right)^{1/2}
\]

(46)

The application of the no-slip boundary condition is not justified. A correct treatment applies the Neumann boundary condition for both the velocity and angular velocity fields; however, this is not straightforward in that the two fields are likely coupled. While the boundary condition for the velocity field has been studied in great detail (e.g., refs 60–62), very little is known about the spin boundary condition. Recently De Luca et al.\(^{63}\) showed that the spin field does possess slippage, and Badur et al.\(^{64}\) used spin slip to account for flow enhancement. As mentioned in the Introduction, we treat the problem in an ad hoc fashion and set the angular velocity slip in accordance with the MD data.

If one ignores the coupling, \( \eta_{r} = 0 \), the solution for the streaming velocity, eq 45a, reduces to the classical Poiseuille flow solution

\[
u_{r}(z') = u_{r} \left( 1 - z'^{2} \right)
\]

(47)
In this classical situation the angular velocity is found from the vorticity, \( \Omega_{z}(z') = \frac{u_{z}}{h} \frac{dz'}{dz} \), that is,
\[
\Omega_{z}(z') = -\frac{u_{z}}{h} \frac{dz'}{dz} = -\frac{hpF}{2\eta_{h}} z' \tag{48}
\]

in agreement with eq 45b for \( \eta \to 0 \). As the classical treatment does not allow for the specification of the spin boundary condition, eqs 45b and 48 differ by order of \( hpF/(2\eta_{h}) \) at the walls.

From eq 45a one can see that the maximum velocity, located at \( z' = 0 \), is lowered as a result of the coupling since from the last term we have \( 1/cosh(Kh) = 1 < 0 \) and thus \( u_{z}(0) < u_{c} \). A way to quantify this effect is to evaluate the volumetric flow rate \( Q \)
\[
Q = \int_{-w}^{w} \int_{-h}^{h} u_{z}(z) dz \ dy = 2w \int_{-h}^{h} u_{z}(z) \ dz \tag{49}
\]

where \( w \) is the half length in the \( y \) direction. This gives the relative volumetric flow rate reduction
\[
\Delta Q^{\text{rel}} = 1 - \frac{Q}{Q_{\text{class}}} = -\frac{3\eta_{h}(\tanh(Kh) - Kh)}{\eta_{h}\tanh(Kh)(Kh)^{2}} \tag{50}
\]

Equation 50 is plotted in Figure 6 for the dumbbell fluid, liquid butane, and water. The relevant coefficients can be found in SI Table 1. For perfect parallel alignment, \( \theta = 0 \), while for perfect perpendicular alignment, \( \theta = 90^\circ \). These conditions are difficult to achieve experimentally, but with \( \theta = 0 \) one can achieve the best possible alignment. The alignment ordering of the fluid is then characterized by the shear viscosity, which is found from the velocity profile.

Table 1. For water flowing in a channel with a width of 9 nm the flow rate is reduced by about 10% due to the coupling. As the channel width increases, the flow rate approaches that of the classical predictions, and the effect of the coupling can be ignored.

From eq 50 the relative flow rate reduction increases as the product \( Kh \) decreases. From this observation, one can define a characteristic fluid length scale \( l_{c}^{\text{ad}} \) below which the effect of the coupling becomes significant. To this end we write the parameter \( K \) as
\[
K = \frac{2}{l_{c}} \frac{\eta_{h}}{\eta_{l}} \text{ with } l_{c} = \sqrt{\frac{\zeta}{\eta_{l}}} \tag{51}
\]

From SI Table 1 it is seen that \( \eta_{0} > \eta_{c} \) and \( K \approx 2/l_{c} \). Thus, a significant flow-rate reduction occurs for fluids with a large critical length scale \( l_{c} \). For water, \( l_{c} = 3.5 \) nm, and for butane, \( l_{c} = 0.5 \) nm in agreement with the relative large flow rate reduction observed for water and low reduction for butane.

2. Comparison with Molecular Dynamics Simulations.

First we compare MD data with continuum predictions for the dumbbell system. Before the comparison, however, the linear Newtonian response regime should be identified, at least for \( p > 0 \)

where \( \theta \) is the angle between the molecular bond and the \( (x_{1}, y_{1}) \) plane. For perfect parallel alignment, \( p = -1/2 \) that is, the molecules closest to the wall are, on average, aligned with the wall. For distances of around one atom diameter the molecules are slightly normal to the wall for \( p > 0 \). The extremes are illustrated
For \( p = 0 \), the molecules have random orientations, which is the case in the interior of the channel. This means that the system possesses a degree of anisotropy in the wall–fluid region. To fully account for the density variation and ordering one should therefore describe the transport properties through a position-dependent tensorial shear viscosity.

Figure 8(a) shows the velocity and density profiles for a butane flow where the pore width is just 6 nm. For such extreme confinements the fluid layering stretches over the entire pore. The order parameter profile, Figure 8(b), shows that the molecular orientation is strongly anisotropic. Finally, the mean square molecular end-to-end distance \( R_{e2} \) also varies, showing that the butane molecule on average is elongated in the fluid-wall region by around 2%. Such a complex system is not modeled appropriately by the classical or extended theories presented here. This is not an indication of a breakdown of the continuum picture but an incomplete modeling. It is worth noting that the fluid ordering and layering are constant over a large range of external forces including zero force (Figure 8) and is thus not flow-induced.

As pointed out by Bitsanis et al.,\(^{71}\) the velocity profile features surprisingly small modulations considering the density profile: one should expect the transport properties to vary significantly across the channel, having large effects on the flow profile. The authors suggested the local average density model (LADM) wherein the transport properties at a point \( z \) are functions of the average density around that point. In the current geometry, where the density is constant in the plane parallel to the wall, the local average density is

\[
\bar{\rho}(z) = \frac{1}{\Delta} \int_{z-\frac{1}{2}\Delta}^{z+\frac{1}{2}\Delta} \rho(z') \, dz'
\]

(53)

where \( \Delta \) defines the region of averaging. The agreement between the LADM and simulation data can be very good, especially if one introduces a nonuniform weighting function.\(^{72}\) However, the LADM cannot predict the shear pressure response in Figure 5 as the density is constant. Also, the LADM model is not capable of predicting the strain rate reversal observed by Travis et al.\(^{11,73}\)

To account for the observed velocity profile one can write the position-dependent (inhomogeneous) nonlocal constitutive model as

\[
P_{xz}(z) = -\int_{-h}^{h} \eta(z, z-z') \dot{\gamma}(z') \, dz'
\]

(54)

The position dependency reflects the varying density in the wall–fluid region. The application of this relation is not straightforward\(^{74,75}\) as it is unclear how the convolution should be performed at the wall where the support of the kernel goes

\[
\text{Figure 7. (a) Velocity and angular velocity profiles for the dumbbell model undergoing Poiseuille flow. Symbols represent MD data, and lines represent the classical predictions where slippage is included. (b) Corresponding shear pressures.} P_{xz} \text{ is calculated by the integration of the momentum balance equation using the density profile given in (c). The antisymmetric pressure is calculated from constitutive relation SIeq 40 using MD data as input. (c) Density and order parameter profiles. The molecules in the lower left corner illustrate (exaggerated) the molecular ordering near the wall.}
\]

with the two molecules in the lower left corner in Figure 7(c). For \( p = 0 \), the molecules have random orientations, which is the case in the interior of the channel. This means that the system possesses a degree of anisotropy in the wall–fluid region. To fully account for the density variation and ordering one should therefore describe the transport properties through a position-dependent tensorial shear viscosity.

\[
\text{Figure 8. (a) Density and velocity profiles for butane in a slit pore of width 6 nm. The prediction from the theory breaks down and is not shown. (b) Corresponding order parameter and square end-to-end distance profiles.}
\]
beyond the boundary and is unknown.\textsuperscript{74,75} Recently, Dalton et al.\textsuperscript{76} used a sinusoidal longitudinal force (SLF), also introduced by Hoang and Galliero,\textsuperscript{72} to control the density variation in a periodic system. Due to the periodicity, the boundary problem can be eliminated. The density profile can be controlled to such an extent that it resembles that seen in confined systems. The fluid can then be driven by an STF. The authors showed that the nonlocal response is capable of predicting the strain rate reversal observed by Travis et al.\textsuperscript{11,73} as well as the relative small modulation in the velocity profile. A rigorous and general implementation of eq 54 into the balance equations for confined systems is still lacking.

For the dumbbell and butane models the coupling between the linear and spin angular velocities has little effect on the flow. From Figure 6, however, the effect is significant for water flow in a channel with widths below 5 nm. In Figure 9(a) MD data for the velocity profile for water is plotted where the channel width is approximately 10 water molecule diameters. Also shown are the predictions from the classical NS and ENS theories. Density and order parameter profiles (not plotted here) show little density variation and molecular alignment, except within 3–4 Å of the wall. The slip velocities are estimated by fitting a second-order polynomial (dashed lines) to the velocity profile, excluding the wall–fluid region where the fluid is slightly anisotropic and inhomogeneous; this then amounts to the apparent slip length\textsuperscript{77} and is the only fitting parameter used in the comparison. It is seen that the classical prediction fails, while the ENS theory much better captures the effect on the velocity profile. Note that the fit of the profile data to the classical description will result in the wrong viscosity no matter how many data points in the wall–fluid region are included. No shift in the profile will change this. An extra source of dissipation must be present. Furthermore, note that a complete description involves a position-dependent nonlocal anisotropic modeling of the wall–fluid region.

To remove any effect in the boundary region one can evaluate the curvature in the midpoint, \( z = 0 \). The predictions are simply found from the second-order derivatives of eqs 45a and 47. The relative difference is

\[
\Delta C^\text{rel} = 1 - \frac{\eta \coth(Kh)K \eta}{(\eta + \eta_0) \coth(Kh)}
\]

(55)

\( \Delta C^\text{rel} \) is plotted in Figure 9(b) together with the results from the MD simulations. Within statistical uncertainty the ENS theory and MD simulation results agree. As the channel width increases, the relative curvature difference vanishes and the classical description is recaptured.

The particular model applied is parametrized with respect to the liquid state, and the wall is a Lennard-Jones cubic lattice; see ref 9. The fluid structure near the wall and its effect on the dynamics will be affected by the different models, choice of model parameters, and wall details. However, it is not the aim here to critically review the fine fluid structure near the wall but to investigate the effect of the coupling.

B. Inserting Torque. Perhaps the most clear illustration of the translational–rotational coupling is seen by introducing an external torque into the system while having a zero production term for the linear momentum. In general, if the resulting torque density \( \rho \mathbf{T}_e \) is sufficiently small, then for the geometry in Figure 1 we have

\[
\eta \frac{d^2u_f}{dz^2} - 2\eta \frac{d\Omega_f}{dz} = 0
\]

(56a)

\[
\rho \Gamma_e + 2\eta \frac{d\eta}{dz} - 2\Omega_f + \zeta \frac{d\Omega_f}{dz} = 0
\]

(56b)

Upon integrating eq 56a we get \( du_f/dz \) in terms of \( \Omega_f \), which is substituted into eq 56b, resulting in a second-order inhomogeneous differential equation for \( \Omega_f \). From this and eq 56a and by application of Dirichlet’s no-slip boundary conditions one has

\[
u_f(z') = \frac{4\eta}{\eta_0} C_1 \sinh(Khz') - \frac{2\eta_0 (\rho \Gamma_e + 2\eta_0 C_0) h}{\eta^2 \zeta K^2} - \frac{C_1 h}{\eta} z'
\]

(57a)

\[
\Omega_f(z') = 2C_1 \cosh(Khz') - \frac{\rho \Gamma_e - 2\eta_0 C_0}{\zeta \eta_0 K^2}
\]

(57b)

where \( C_0 \) and \( C_1 \) are integration constants. One can show that \( C_1 \) goes rapidly to zero as \( h \) increases. In this limit the spin angular velocity is

\[
\Omega_f(z') = \frac{\Gamma_e}{\zeta K^2} - \frac{4\rho \Gamma_e h^2 \eta K}{(\eta_0^2 K^2)^2 - 4\eta_0 \eta K^2} (\text{large } h)
\]

(58)

and the velocity profile is linear with a slope given by the last term in eq 57a. Figure 10 depicts the two profiles for the butane liquid using \( \Gamma_e = 413 \text{ m }^2 \text{ s}^{-3} \). From this, one sees that the external torque produces a significant local flow; the average flow is zero due to the system symmetry.

In 2009, Bonthuis et al.\textsuperscript{78} showed that the coupling between the linear momentum and spin could be exploited in order to pump water through carbon nanotubes by the application of a rotating field. The theory was based on the ENS equations and it was noted that in order to obtain a nonzero mean flow, asymmetric boundary conditions must be employed which can be achieved by confining the fluid between two walls with different hydrophobities in the case of water pumping. Recently De Luca et al.\textsuperscript{63} performed extensive MD simulations of the

\ DOI: 10.1021/acs.langmuir.6b02237

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Figure 9. (a) Velocity profiles of water undergoing Poiseuille flow. (b) Relative profile curvature difference at \( z = 0 \). From ref 9 with modifications.
We conclude that continuum theory is applicable even on the nanoscale if the relevant physical processes are modeled appropriately.

**ASSOCIATED CONTENT**

* Supporting Information
The Supporting Information is available free of charge on the ACS Publications website at DOI: 10.1021/acs.langmuir.5b02237.

Balance equations and the extended Navier–Stokes equation. Schematic illustration of the interactions between two molecules i and j. (PDF)

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**Figure 10.** Flow of butane as a result of applying an external torque. The inset shows the corresponding angular velocity normalized with respect to the value in the limit of large $h$, eq 58, here denoted as $\Omega_{\text{cr}}$. We conclude that continuum theory is applicable even on the nanoscale if the relevant physical processes are modeled appropriately.
nonlinear response theory, and rheology, he has for many years worked on the physics of highly viscous liquids and the glass transition. Since 2005 he has directed the theoretical and experimental DNRF Centre “Glass and Time”, the research of which has gradually expanded from focusing exclusively on glass-forming liquids to including the structure and dynamics of liquids and solids in general. He is a member of the Royal Danish Academy of Sciences and Letters.

Peter Davis received his undergraduate and masters degrees in applied physics at RMIT University, a graduate diploma in applied colloid science at Swinburne University, and a Ph.D. in physics at Massey University (New Zealand). After completing his Ph.D., he was appointed to a postdoctoral position at the Australian National University. In 1995, he returned to RMIT University, where he has been a professor of physics since 2011. His research has included experimental, computational, and theoretical studies of soft matter, and his current research interests are centred on nonequilibrium statistical and thermal physics, computational nanofluidics, and generalized hydrodynamics.

Billy D. Todd did his undergraduate and postgraduate studies in physics in Australia. He then completed postdoctoral appointments at the University of Cambridge and the Australian National University before moving to CSIRO in Melbourne in 1996. In 1999 he took up an academic appointment at Swinburne University of Technology, where he is currently a professor and Chair of the Department of Mathematics. His research speciality is in statistical mechanics, nonequilibrium molecular dynamics, and computational nanofluidics. He is a fellow of the Australian Institute of Physics and a former president of the Australian Society of Rheology.

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### ACKNOWLEDGMENTS

We acknowledge Lundbeckfonden for supporting this work as part of grant no. R49-A5634. The Centre for Viscous Liquid Dynamics “Glass and Time” is sponsored by the Danish National Research Foundation via grant DNRF 61.

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DOI: 10.1021/acsl.langmuir.6b02237

Langmuir XXX, XXX, XXX–XXX
Invited Feature Article

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